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type of controller based on the combined integrating systems is proposed, which is called a combined integrating controller. The controller's current output is determined only by the current input and the average value of the controller's previous output. The innovation is to introduce a time-delay positive feedback in the controller.

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as to tend to reduce the deviation to zero."

Control theory - Wikipedia

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2.44 Mechanical

system for Problem 2.2

Solution: The key is to

draw the Free Body

Diagram (FBD) in order

to keep the signs right.

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